



## FPV POLAR XC3000 Brushless DC Motor First-Person View

### Our Product Introduction

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#### Basic Information

- Place of Origin: Guangdong, China
- Brand Name: GS
- Model Number: XC3000 650KV 920KV 1200KV
- Price: Negotiable

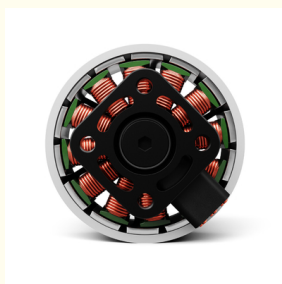


#### Product Specification

- Motor Model: Polar Xc3000 V1.0
- Motor Size: D:35.7 X40.55 Mm
- Propeller Mounting Holes: M5 Nut
- Shaft Diameter: IN:5 Mm
- Bearing: 688 \*4
- Motor Number Of Slots: 12N14P
- Rotor Balance:  $\leq 5\text{mg}$
- Motor Balance: D:19 M3x4
- Cable Length: 380 Mm 18# Awg(Black)silicone
- Highlight: **FPV POLAR XC3000 Brushless DC Motor, XC3000 Brushless DC Motor, First-Person View Brushless DC Motor**



#### More Images



## FPV POLAR XC3000 Brushless DC Motor First-Person View

XC3000 POLAR motor is best choose for MacroQuad-7/8/9/10" quad:

1. Weighs 70g with 2pcs durable bearing;
2. Maximum thrust can reach 2.8kg.

FPV POLAR XC3000 Brushless DC Motor\*\* is likely a robust and powerful motor designed for high-performance FPV drones. Its features suggest it would be well-suited for demanding applications, such as long-range flights, heavy-lift aerial photography, or high-speed racing. With a focus on durability and efficiency

# POLAR XC3000

ENERGY EFFICIENT 650KV  
ENTHUSIASTS EXTREME EDITION

700~900 gf  
RECOMMENDED  
HOVER THRUST

OPTIMIZED  
WEIGHT 70g

2.8 kgf



MAXIMUM  
THRUST

MAXIMUM THRUST MAY DEPEND ON  
BATTERY LEVEL, PROPELLER TYPE,  
AIR PRESSURE AND OTHER CONDITIONS

EFFICIENCY >79%

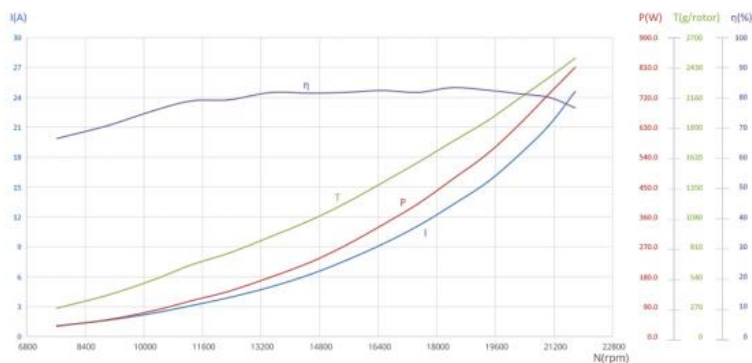


MAD Polar XC3000 EEE 650KV HQ 7x4.5x3 Carbon Fiber BLHeli-32 50A 8S-12S 4IN1 ESC 12S MAX 97°C

### Analytical Graph of Motor Operation

I - Current, P - Input Power,  $\eta$  - Electrical Efficiency, T - Thrust, N - Rotational Speed

The data above was measured with an input voltage of 48 V, at a temperature of 25°C and sea level. The rotational speed was adjusted by the throttle.

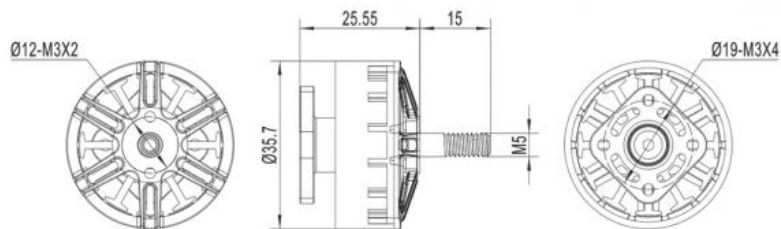


### Motor Data

Motor Model	MAD Polar XC3000 EEE V1.0	Number of pole pairs	7
Stator	TAIWAN / Anticorrosive	Varnished wire Degree	180°C
Motor Size	D:35.7 × 40.55 mm	Magnet Degree	150°C
Degree of Protection	Rain protection	Cable Length	380 mm 18# Awg(Black) silicone
Centrifugal Heat Dissipation	Independent	Rotor Balance	≤5 mg
Propeller Mounting Holes	M5 Nut	Motor Balance	≤10 mg
Shaft Diameter	IN: 5 mm	Motor Mounting Holes	D:19 M3×4
Bearing	NSK 684ZZ *2	Disruptive test	500 V
Additional Accessories	M3*8mm *4 Motor Screws, M5 Nut Propeller Screws, Sticker*2		

### Specifications

RPM/V	650 KV	Nominal Voltage	8-12S lipo battery
No Load Current	0.6A/10V	Internal resistance	28.7mΩ
Motor Weight	70 g	Product Boxed Weight	490 g (110 x 110 x 95 mm)
Maximum Current	28.2 A	Maximum Power	1330W
Maximum thrust	2.8 kg	Maximum Torque	0.4 Nm
Recommended ESC	BLHeli-32 50A 8S-12S 4IN1 ESC	Recommended Propellers	HQ 7x4.5x3, HQ 8x4.5x3, HQ 9x5x3
UAV take-off weight	8S-7/ 3.2kg--Quadcopter 4.8kg--Hexacopter 6.4kg--Octocopter	Single rotor take-off weight	700g ~ 900g



MAD Polar XC3000 EEE 650KV HQ 8x4.5x3 Carbon Fiber BLHeli-32 50A 8S-12S 4IN1 ESC

8S

MAX  
92°C

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	32.08	1.15	36.8	25.8	0.046	5374	265	70.75	7.3
35	32.06	1.66	53.2	38.1	0.060	6108	353	72.31	6.7
40	32.05	2.24	71.7	54.0	0.075	6843	449	75.7	6.3
45	32.02	3.1	99.3	76.9	0.096	7672	577	77.83	5.8
50	31.99	4.2	134.4	105.9	0.118	8538	704	80.7	5.4
55	31.96	5.55	177.5	141.1	0.145	9298	869	82.09	5.1
60	31.92	6.97	222.4	176.5	0.168	10025	1006	81.82	4.7
65	31.88	8.55	272.4	214.5	0.191	10710	1150	81.06	4.3
70	31.83	10.33	328.8	257.3	0.217	11308	1301	80.42	4.1
75	31.77	12.39	393.8	305.1	0.244	11922	1477	79.48	3.8
80	31.71	14.68	465.4	355.5	0.271	12505	1632	78.15	3.6
85	31.65	17.21	544.5	406.0	0.297	13040	1804	76.13	3.4
90	31.58	19.67	621.0	455.0	0.320	13567	1915	74.64	3.1
95	31.49	22.62	712.3	506.3	0.345	14009	2065	72.21	2.9
100	31.42	25.47	800.5	551.9	0.365	14446	2174	69.87	2.8

MAD Polar XC3000 EEE 650KV HQ 9x5x3 Carbon Fiber BLHeli-32 50A 8S-12S 4IN1 ESC

8S

MAX  
113°C

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	31.77	1.45	46.0	34.0	0.064	5105	349	76.18	7.8
35	31.76	2.12	67.5	51.2	0.084	5801	466	78.24	7.1
40	31.73	3	95.2	72.8	0.107	6494	603	78.42	6.5
45	31.7	4.15	131.6	102.6	0.135	7234	766	80.01	6.0
50	31.66	5.63	178.2	137.6	0.165	7973	931	79.1	5.4
55	31.61	7.47	236.1	180.2	0.199	8653	1127	77.96	4.9
60	31.57	9.31	294.0	221.6	0.228	9293	1291	76.84	4.5
65	31.51	11.51	362.6	267.0	0.259	9858	1467	74.86	4.1
70	31.45	13.82	434.6	313.0	0.288	10370	1628	73.1	3.8
75	31.38	16.33	512.5	356.1	0.314	10820	1786	70.36	3.5
80	31.32	18.68	585.0	398.3	0.340	11202	1914	68.8	3.3
85	31.25	21.58	674.2	437.6	0.362	11528	2040	65.42	3.1
90	31.17	24.31	757.6	470.9	0.380	11820	2138	62.5	2.8
95	31.09	27.14	843.8	495.8	0.393	12039	2214	58.9	2.6
100	30.99	30.54	946.4	528.2	0.411	12273	2314	57.6	2.5

MAD Polar XC3000 EEE 650KV    HQ 10x4.5    BLHeli-32 50A 8S-12S 4IN1 ESC

8S    MAX  
118℃

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	32.06	1.34	43.1	31.1	0.057	5229	358	72.82	8.4
35	32.04	1.94	62.2	46.4	0.075	5944	465	75.24	7.5
40	32.03	2.72	87.0	65.7	0.094	6657	586	75.92	6.8
45	32	3.79	121.4	94.3	0.121	7437	756	78.7	6.3
50	31.96	5.2	166.1	128.8	0.150	8201	918	80.09	5.7
55	31.91	6.92	220.8	170.6	0.183	8919	1103	79.62	5.2
60	31.87	8.79	280.1	214.1	0.214	9539	1266	78.68	4.7
65	31.8	11.07	352.2	262.9	0.249	10091	1452	76.63	4.2
70	31.74	13.38	424.7	310.5	0.279	10614	1605	74.93	3.9
75	31.67	15.88	502.9	355.6	0.307	11067	1734	72.28	3.5
80	31.61	18.31	578.6	400.1	0.333	11475	1860	70.51	3.3
85	31.52	21.41	674.8	448.4	0.364	11768	2005	67.57	3.0
90	31.45	24.29	763.9	481.8	0.382	12033	2089	63.97	2.8
95	31.37	27.14	851.5	505.9	0.395	12235	2156	60.12	2.6
100	31.27	30.72	960.9	539.1	0.416	12452	2245	56.6	2.4

MAD Polar XC3000 EEE 650KV    HQ 7x4.5x3 Carbon Fiber    BLHeli-32 50A 8S-12S 4IN1 ESC

12S    MAX  
97℃

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	44.28	1.08	47.8	31.1	0.039	7623	256	66.34	5.5
35	44.26	1.64	72.6	50.8	0.054	9011	374	70.67	5.2
40	44.25	2.37	104.8	78.6	0.073	10292	516	75.76	5.0
45	44.23	3.12	138.1	108.2	0.091	11312	649	78.96	4.7
50	44.2	3.9	172.5	135.9	0.105	12307	751	79.28	4.4
55	44.17	4.99	220.5	179.2	0.127	13472	903	81.74	4.1
60	44.14	6.26	276.3	224.4	0.147	14562	1052	81.54	3.8
65	44.11	7.64	337.0	274.8	0.169	15517	1206	81.79	3.6
70	44.06	9.26	408.1	335.7	0.194	16508	1388	82.44	3.4
75	44.02	11.1	488.8	399.5	0.218	17484	1572	81.79	3.2
80	43.96	13.22	581.0	473.8	0.245	18432	1761	83.38	3.1
85	43.89	15.52	681.4	550.8	0.271	19388	1949	82.53	2.9
90	43.82	18.29	801.7	639.8	0.302	20264	2153	81.32	2.7
95	43.74	21.22	928.4	731.0	0.331	21071	2340	80.09	2.6
100	43.65	24.59	1073.4	810.1	0.355	21779	2515	76.6	2.4

MAD Polar XC3000 EEE 650KV    HQ 7x4.5x3 Carbon Fiber    BLHeli-32 50A 8S-12S 4IN1 ESC

12S    MAX  
129℃

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	47.88	1.26	60.6	39.3	0.045	8262	315	66.57	5.3
35	47.87	1.94	93.1	65.6	0.064	9786	464	72.05	5.1
40	47.85	2.71	129.7	96.7	0.084	10987	610	76.27	4.8
45	47.83	3.47	165.9	125.9	0.099	12086	720	77.36	4.4
50	47.8	4.49	214.5	169.5	0.122	13232	878	80.52	4.2
55	47.77	5.79	276.7	222.2	0.147	14453	1052	81.72	3.9
60	47.74	7.21	344.1	275.4	0.170	15502	1238	81.39	3.7
65	47.69	8.87	423.3	340.4	0.196	16617	1417	81.71	3.4
70	47.64	10.7	509.7	413.0	0.224	17645	1621	82.16	3.2
75	47.57	12.97	617.1	496.0	0.254	18634	1846	81.39	3.0
80	47.52	15.36	729.8	582.8	0.284	19616	2066	80.72	2.9
85	47.44	18.12	859.6	683.6	0.318	20549	2242	80.25	2.6
90	47.36	21.35	1011.2	775.1	0.347	21335	2439	77.24	2.4
95	47.26	24.42	1154.2	867.7	0.374	22149	2631	75.58	2.3
100	47.17	28.2	1330.1	966.2	0.406	22752	2840	72.9	2.1

The above data are the theoretical values when the input voltage is 48V, for reference only. In the case of room temperature of 25℃ and no additional cooling device, the current over 28A is non-working zone.9-28A is short-term (about 10-30s), working zone, and below 9A is sustainable working zone. In actual use, please control the motor running time according to the working environment temperature and heat dissipation conditions.



# POLAR XC3000

ENERGY EFFICIENT 920KV  
ENTHUSIASTS EXTREME EDITION

700~900 gf  
RECOMMENDED  
HOVER THRUST

OPTIMIZED  
WEIGHT 70g

2.5 kgf  
MAXIMUM  
THRUST

EFFICIENCY >83%

MAXIMUM THRUST MAY DEPEND ON  
BATTERY LEVEL, PROPELLER TYPE,  
AIR PRESSURE AND OTHER CONDITIONS



MAD Polar XC3000 EEE 920KV HQ 7x4.5x3 Carbon Fiber BLHeli-32 50A 8S-12S 4IN1 ESC

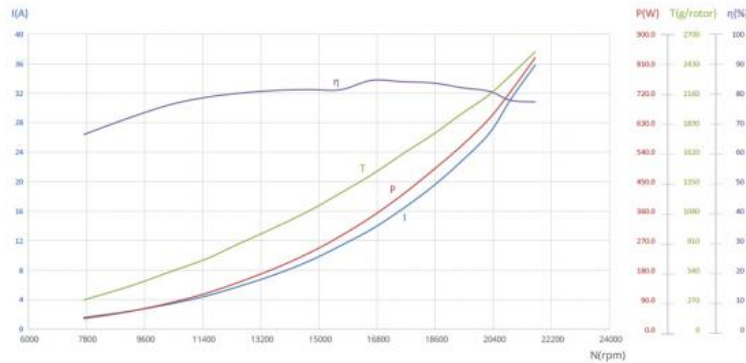
8S

MAX  
96°C

## Analytical Graph of Motor Operation

I - Current, P - Input Power,  $\eta$  - Electrical Efficiency, T - Thrust, N - Rotational Speed

The data above was measured with an input voltage of 32 V, at a temperature of 25°C and sea level. The rotational speed was adjusted by the throttle.



## Specifications

RPM/V	920 KV	Nominal Voltage	6-8S lipo battery
No Load Current	1.0A/10V	Internal resistance	57mΩ
Motor Weight	70 g	Product Boxed Weight	490 g (110 x 110 x 95 mm)
Maximum Current	39.6 A	Maximum Power	1088W
Maximum thrust	2.5 kg	Maximum Torque	0.4 Nm
Recommended ESC	MAD BL-32 60A 4IN1 6S 64MHZ ESC BLHeli-32 50A 8S-12S 4IN1 ESC	Recommended Propellers	HQ 7x4.5x3, GF 8040x3
UAV take-off weight	8S-7" 3.2kg--Quadcopter 4.8kg--Hexacopter 6.4kg--Octocopter	Single rotor take-off weight	700g ~ 900g

MAD Polar XC3000 EEE 920KV GF 7035x3 MAD BL-32 60A 4IN1 6S 64MHZ ESC

6S

MAX  
81°C

Throttle (%)	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [gf]	Efficiency [%]	Efficiency [g/W]
30	23.89	1.13	27.1	15.1	0.023	6343	165	59.46	6.5
35	23.88	1.61	38.5	24.0	0.031	7359	231	65.06	6.3
40	23.89	2.33	55.7	37.3	0.042	8456	310	70.24	5.8
45	23.84	3.08	73.5	52.9	0.053	9540	407	74.98	5.8
50	23.83	3.93	93.7	69.8	0.064	10485	488	77.59	5.4
55	23.81	4.91	116.9	90.0	0.076	11292	590	79.95	5.2
60	23.8	6.01	143.0	112.8	0.089	12170	686	81.78	5.0
65	23.77	7.33	174.3	138.8	0.102	13019	801	82.41	4.8
70	23.74	8.7	206.5	168.2	0.116	13870	905	84.26	4.5
75	23.71	10.43	247.4	204.3	0.133	14722	1038	85.29	4.3
80	23.68	12.21	289.1	239.5	0.147	15559	1163	85.41	4.2
85	23.64	14.37	339.7	282.9	0.165	16409	1303	85.69	3.9
90	23.6	16.62	392.1	326.0	0.180	17248	1434	85.36	3.8
95	23.56	19.17	451.5	374.3	0.198	18060	1585	84.97	3.6
100	23.49	22.62	531.4	438.5	0.220	19053	1750	84.32	3.4

6S MAX  
93°C

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N•m]	RPM	Thrust [gf]	Efficiency [%]	Efficiency [gf/W]
30	23.88	1.74	41.7	29.4	0.046	6100	286	73.77	7.2
35	23.86	2.48	59.3	42.3	0.058	6973	384	74.65	6.8
40	23.84	3.5	83.5	63.0	0.077	7856	511	78.74	6.4
45	23.82	4.94	117.6	90.9	0.098	8832	659	80.19	5.8
50	23.79	6.59	156.8	124.5	0.122	9715	825	82.35	5.5
55	23.76	8.31	197.6	158.4	0.144	10543	966	83.06	5.1
60	23.72	10.21	242.3	193.9	0.164	11312	1115	82.66	4.8
65	23.67	12.63	299.0	240.8	0.191	12059	1292	82.94	4.5
70	23.63	15.2	359.0	286.4	0.214	12787	1451	82.03	4.2
75	23.58	17.86	421.2	335.2	0.237	13523	1607	81.67	3.9
80	23.52	21.18	498.1	390.4	0.263	14194	1786	80.2	3.7
85	23.46	24.8	581.8	450.7	0.290	14827	1979	79.04	3.5
90	23.38	28.71	671.3	508.4	0.315	15393	2146	76.99	3.3
95	23.31	32.65	760.9	567.3	0.339	15978	2291	75.53	3.1
100	23.2	38.33	889.3	634.3	0.366	16566	2478	71.95	2.8

6S MAX  
90°C

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	23.89	1.82	43.4	30.2	0.051	5682	303	73.04	7.3
35	23.87	2.56	61.2	43.9	0.065	6453	386	74.97	6.6
40	23.86	3.47	82.7	61.7	0.082	7207	489	77.88	6.2
45	23.81	4.87	115.9	88.3	0.105	8048	629	79.16	5.6
50	23.77	6.65	158.1	122.7	0.131	8928	789	80.39	5.2
55	23.71	8.57	203.3	157.3	0.155	9675	937	79.84	4.8
60	23.66	10.75	254.3	197.2	0.181	10423	1082	79.89	4.4
65	23.59	13.4	316.0	242.9	0.208	11152	1254	78.95	4.1
70	23.51	16.2	381.0	292.3	0.237	11753	1416	78.52	3.8
75	23.43	19.37	453.7	342.5	0.264	12374	1578	76.93	3.5
80	23.33	22.96	535.7	398.6	0.294	12928	1758	75.51	3.3
85	23.23	26.31	611.1	448.0	0.317	13484	1872	74.05	3.1
90	23.12	30.48	704.8	503.7	0.345	13958	2031	71.86	2.9
95	23	35	804.9	557.1	0.370	14364	2181	70.55	2.8
100	22.87	39.56	904.9	605.3	0.392	14753	2294	69.54	2.6

8S MAX  
96°C

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [g]	Efficiency [%]	Efficiency [g/W]
30	31.28	1.58	49.3	32.0	0.040	7719	267	65.94	5.5
35	31.26	2.42	75.7	53.4	0.056	9131	392	71.62	5.3
40	31.24	3.47	108.3	81.6	0.075	10457	531	76.23	5.0
45	31.21	4.51	140.6	109.5	0.091	11519	643	78.56	4.6
50	31.18	5.69	177.3	140.4	0.108	12448	771	79.82	4.4
55	31.13	7.39	230.0	185.0	0.130	13637	930	80.86	4.1
60	31.08	9.27	288.0	232.9	0.151	14716	1085	81.15	3.8
65	31.03	11.28	350.0	283.1	0.173	15657	1243	81.08	3.6
70	30.97	13.59	420.8	343.5	0.197	16648	1415	84.31	3.5
75	30.89	16.35	505.2	411.1	0.223	17605	1605	83.79	3.3
80	30.81	19.4	597.6	485.1	0.250	18538	1782	83.38	3.1
85	30.72	22.87	702.5	560.9	0.276	19440	1974	81.77	2.9
90	30.61	26.65	815.7	643.8	0.303	20293	2149	80.52	2.7
95	30.5	31.2	951.4	725.2	0.331	20945	2324	77.47	2.5
100	30.36	35.82	1087.5	827.6	0.364	21698	2537	76.98	2.4

The above data are the theoretical values when the input voltage is 32V, for reference only. In the case of room temperature of 25°C and no additional cooling device, the current over 36A is non-working zone, 11-36A is short-term (about 10-30s), working zone, and below 11A is sustainable working zone. In actual use, please control the motor running time according to the working environment temperature and heat dissipation conditions.

# POLAR XC3000

ENERGY EFFICIENT 1200KV  
ENTHUSIASTS EXTREME EDITION

700~900 gf  
RECOMMENDED  
HOVER THRUST  
  
OPTIMIZED  
WEIGHT 70g

2.5 kgf  
MAXIMUM  
THRUST  
MAXIMUM THRUST MAY DEPEND ON  
BATTERY LEVEL, PROPELLER TYPE,  
AIR PRESSURE AND OTHER CONDITIONS.  
  
EFFICIENCY >75%



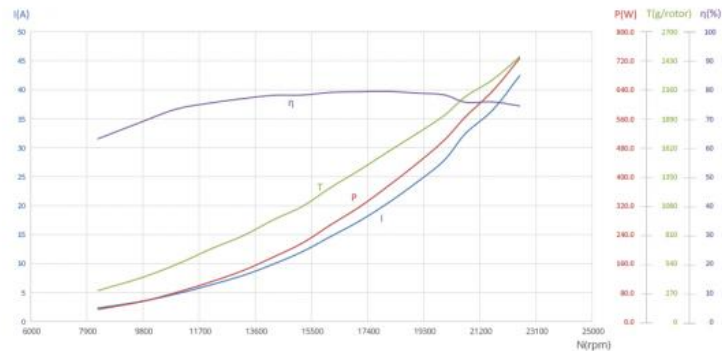
MAD Polar XC3000 EEE 920KV GF 7035x3 MAD BL-32 60A 4IN1 6S 64MHZ ESC

6S MAX  
98°C

## Analytical Graph of Motor Operation

I - Current, P - Input Power,  $\eta$  - Electrical Efficiency, T - Thrust, N - Rotational Speed

The data above was measured with an input voltage of 24 V, at a temperature of 25°C and sea level. The rotational speed was adjusted by the throttle.



## Specifications

RPM/V	1200 KV	Nominal Voltage	6S lipo battery
No Load Current	1.6A/10V	Internal resistance	39mΩ
Motor Weight	70 g	Product Boxed Weight	490 g (110 x 110 x 95 mm)
Maximum Current	42 A	Maximum Power	981W
Maximum thrust	2.5 kg	Maximum Torque	0.3 Nm
Recommended ESC	MAD BL-32 60A 4IN1 6S 64MHZ ESC	Recommended Propellers	GF 7035x3
UAV take-off weight	6S-77 3.2kg--Quadcopter 4.8kg--Hexacopter 6.4kg--Octocopter	Single rotor take-off weight	700g - 900g

MAD Polar XC3000 EEE 1200KV GF 7035x3 MAD BL-32 60A 4IN1 6S 64MHZ ESC

6S MAX  
98°C

Throttle [%]	Voltage [V]	Current [A]	Input Power [W]	Output Power [W]	Torque [N·m]	RPM	Thrust [gf]	Efficiency [%]	Efficiency [g/W]
30	23.86	2.34	55.9	33.8	0.039	8280	289	63.1	5.4
35	23.84	3.5	83.5	55.1	0.054	9757	409	68.92	5.1
40	23.82	4.81	114.7	81.0	0.071	10953	534	73.41	4.8
45	23.79	6.33	150.5	109.5	0.086	12095	676	75.46	4.7
50	23.75	7.98	189.6	141.2	0.102	13199	801	76.99	4.4
55	23.72	9.93	235.5	178.2	0.120	14218	949	78.1	4.2
60	23.68	12.05	285.4	216.5	0.136	15190	1072	78.2	3.9
65	23.63	14.68	347.0	267.1	0.158	16154	1249	79.11	3.7
70	23.58	17.44	411.2	318.2	0.177	17160	1417	79.35	3.5
75	23.51	20.59	484.2	376.1	0.198	18131	1589	79.45	3.4
80	23.45	24.06	564.4	436.4	0.218	19078	1753	78.86	3.2
85	23.4	27.8	650.3	500.3	0.239	19992	1919	78.27	3.0
90	23.31	32.48	756.9	565.7	0.261	20723	2097	75.73	2.8
95	23.23	36.46	847.0	636.1	0.281	21630	2252	75.85	2.7
100	23.12	42.44	981.2	726.8	0.308	22554	2467	74.45	2.5

The above data are the theoretical values when the input voltage is 24V, for reference only. In the case of room temperature of 25°C and no additional cooling device, the current over 42A is non-working zone, 15-42A is short-term (about 10-30s) working zone, and below 15A is sustainable working zone. In actual use, please control the motor running time according to the working environment temperature and heat dissipation conditions.

Our Services

1. We provide 1 Year Warranty. Buy with confidence.
2. If you are not satisfied when you receive your item, please return it within 14 days for a replacement or money back. Please contact me before you return it.
3. If item is defective in 3 months, We will send you a replacement without extra charger, or offer refund after we receive the defective item.
4. If item is defective after 3 months, you can still send it back to us. We will send you a new one after receiving the defective item. But you have to pay the extra shipping fee.



## FAQ

Q1: Do you support OEM/ODM?

A1: Yes. We can print your logo on the product.

Q2: About samples.

A2: Under normal circumstances, samples will be ready within 7 days, and 10-20 days for OEM/ODM orders. Sample fee and shipping will be charged.

Q3: What is the delivery time?

A3: For regular orders, we can ship within 15 days, for OEM/ODM, we can ship within 25-45 days (depending on the quantity). In the event of delays, we will notify you in advance of the status and resolution.

Q4: What is the minimum order quantity?

A4: There is no MOQ for wholesale (1 piece accepted), including OEM/ODM.

Q5: What are your payment terms?

A5: L/C.TT100%.

Q6: Can you reduce the shipping cost?

A6: When calculating the shipping cost for you, we always choose the cheapest and safest express. Although we have partnerships with shipping companies, we can't keep costs down because it's not us who get paid. If you think it's expensive for you. You can always make your own choice.

Q7: Return policy.

A7: If you want to replace the received item, you must contact us within 7 days after receiving the item. Returned items should be in their original condition and you should pay for additional shipping.



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uav-vtoldrone.com

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